# Hydraulic Systems Digitalization
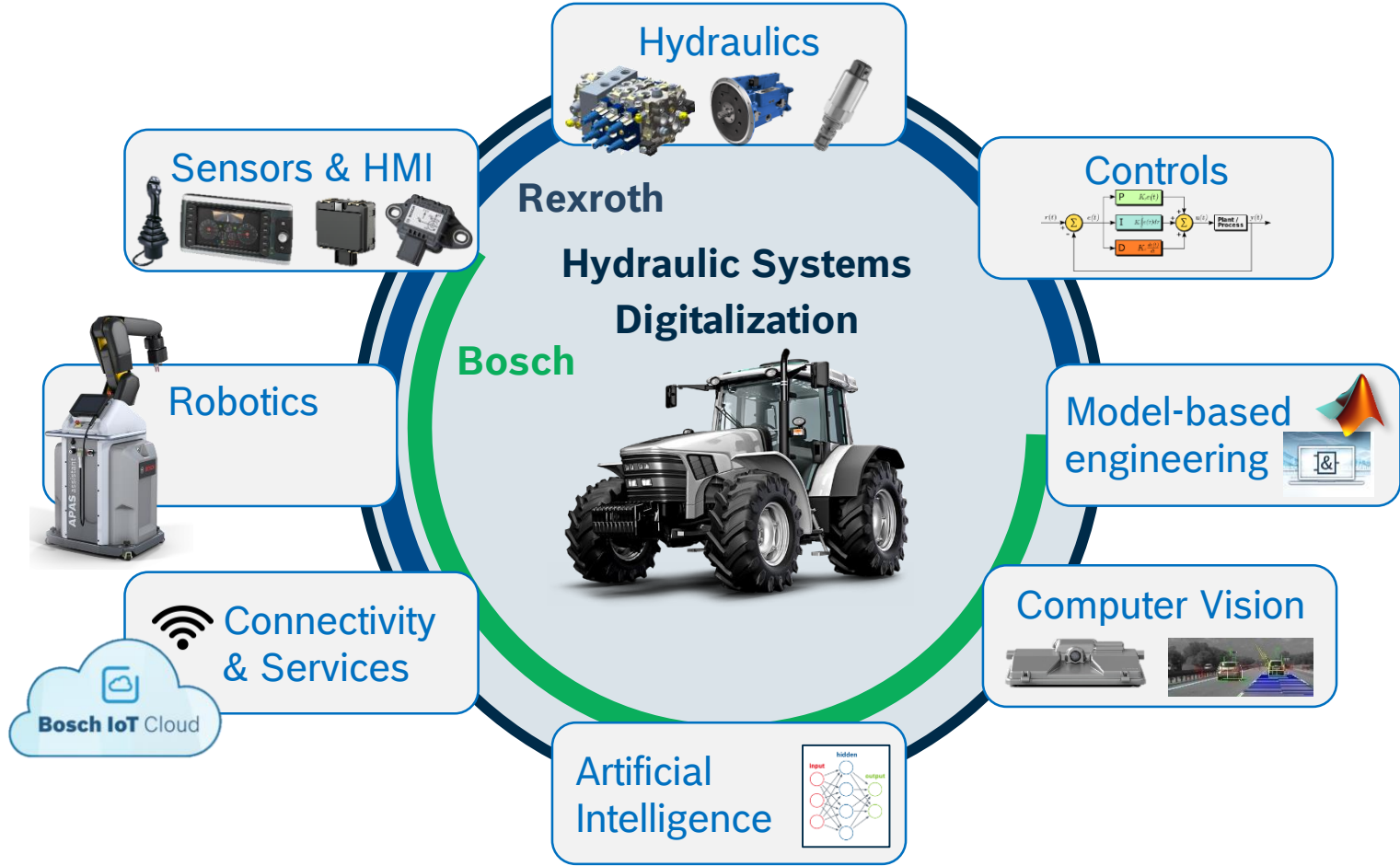
**Enrique Busquets**
Engineering Manager – Mobile Systems and Electronics

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# Hydraulic Systems Digitalization
## Unleashing Hydraulics Through Electronics



Hydraulics

Sensors & HMI

Controls

Rexroth

Hydraulic Systems Digitalization

Bosch

Robotics

Model-based engineering

Connectivity & Services

Bosch IoT Cloud

Computer Vision

Artificial Intelligence
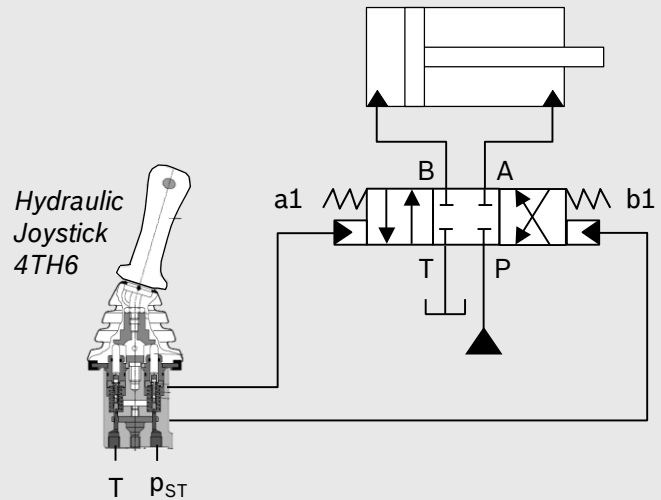
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# Hydraulic Systems Digitalization
## Unleashing Hydraulics Through Electronics

### Hydraulic Pilot Control (Non-EH System)

- Driver demand is given by hydraulic pilot pressure
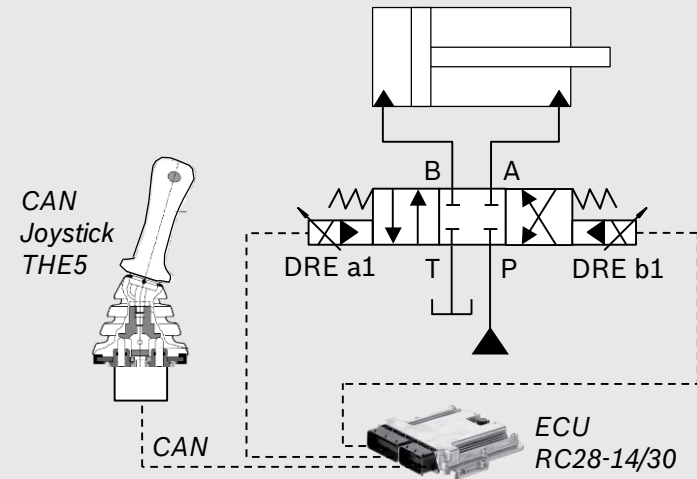- No electronics, no software

*Hydraulic Joystick 4TH6*

a1    B    A    b1

T    P

T   $p_{ST}$

**No possibility to manipulate driver demand**

### VS.

### Electro-Hydraulic Pilot Control (EH System)

- Driver demand is given by electronic joystick
- Software computes the actuation currents for DREs

*CAN Joystick THE5*

B    A

DRE a1   T    P    DRE b1

*CAN*

*ECU RC28-14/30*

**Driver demand can be manipulated by software**

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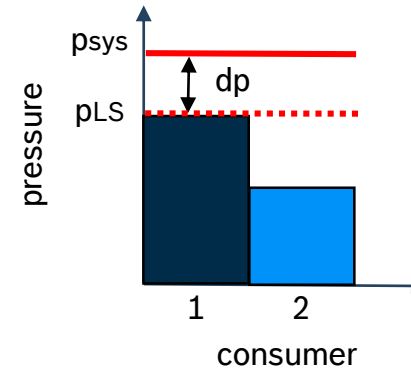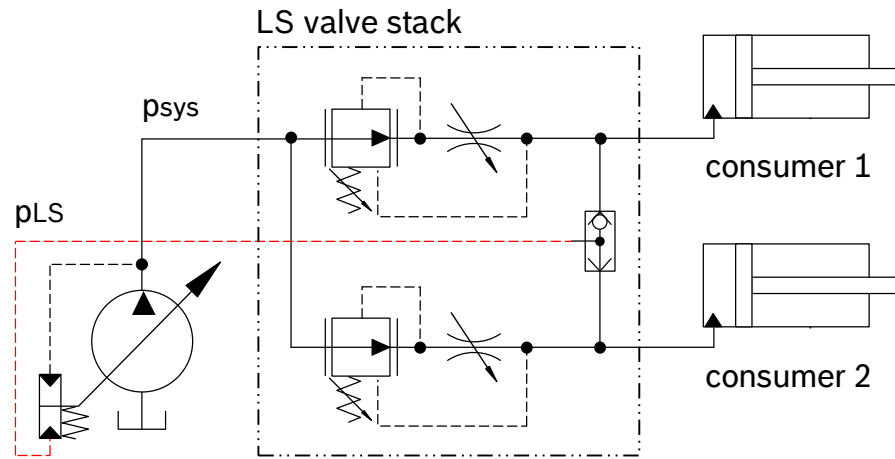# Traditional Load Sensing Hydraulics
## Working Principle
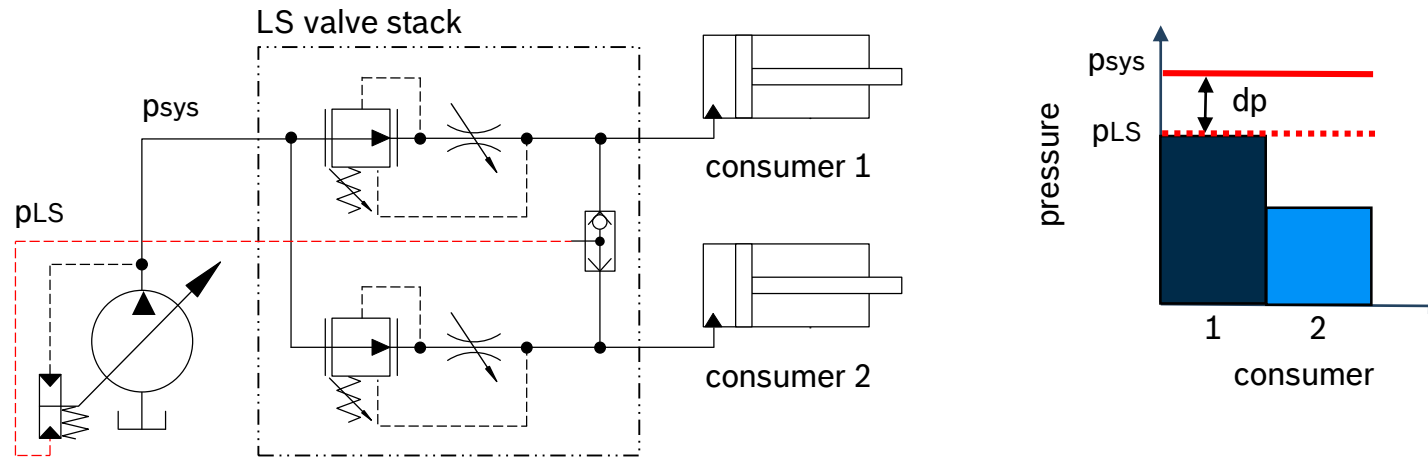


- Pump operates in a closed-loop control with reference on the highest load pressure

- This load pressure generally exhibits large changes

- Additional uncertainties exist in the system (i.e. changes in temperature, natural frequencies and damping).

> A fixed setting of the pump's control parameters must be a compromise across all operating conditions
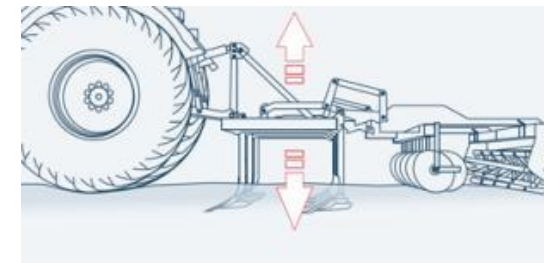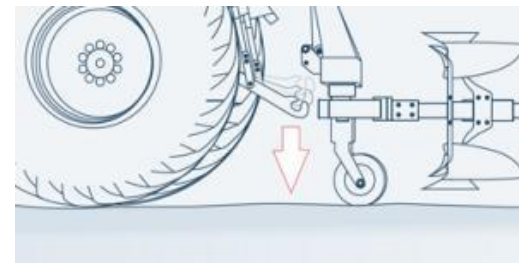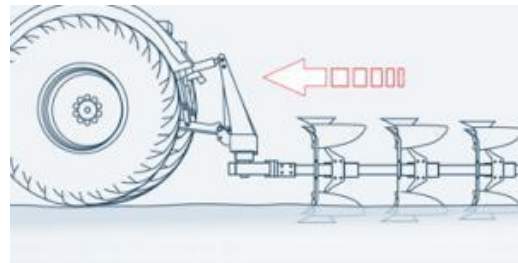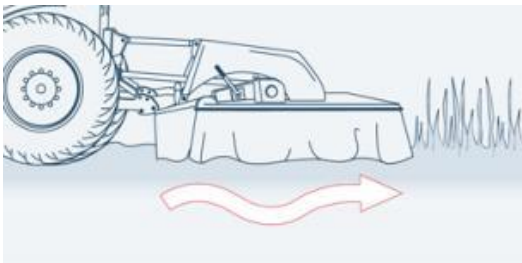
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# Traditional Load Sensing Hydraulics
## Working Principle



LS valve stack

psys

pLS

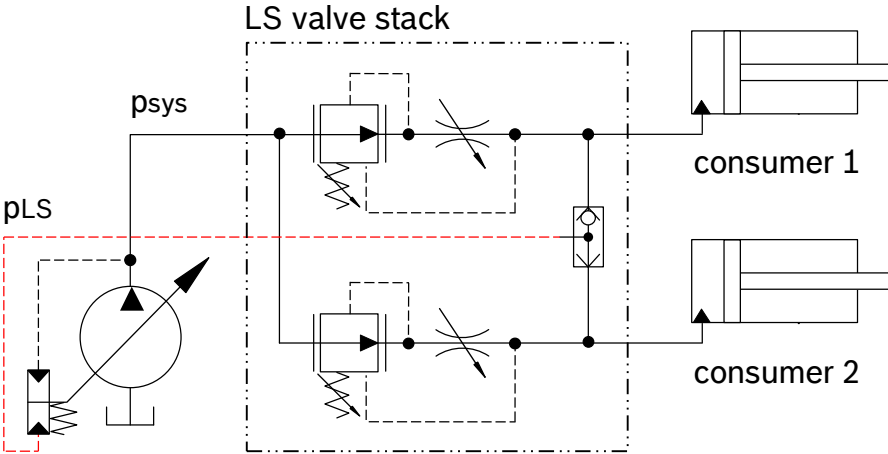consumer 1

consumer 2

psys

pLS

dp

pressure

1    2

consumer

In tractor applications, one setting has to cover:

- Multiple different implements
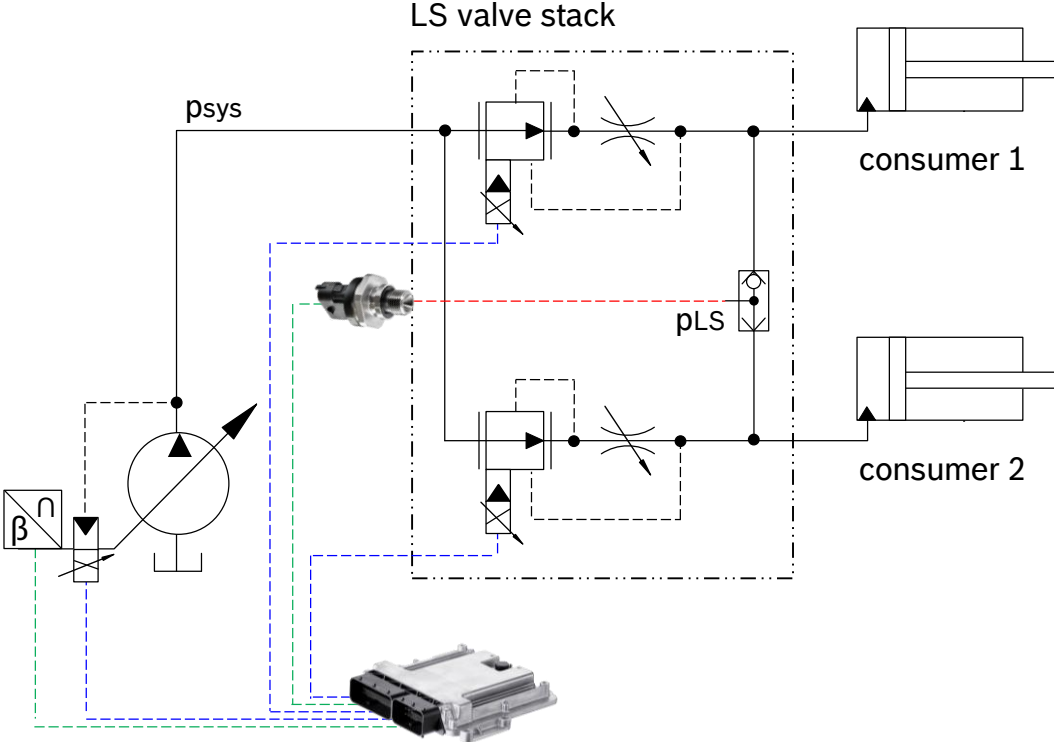- Varying working conditions & processes
- Individual driver preferences

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# Load Sensing Hydraulics
## Architecture Comparison

**Hydraulic Load Sensing (traditional)**

**Electronic Load Sensing**

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# e-LS Advances Load-Sensing Systems

**Open Center**
One pump

**Open Center**
Multiple pumps

+ Oil-flow
+ Energy

**Open Center Load Sensing**

++ Efficiency
+ Controllability
+ Oil-flow

**Closed Center Load Sensing**

+++ Efficiency
++ Controllability
++ Oil-flow

**e-LS**

+++ Efficiency
++  Controllability
++ Oil-flow
**+ Operating Modes**
**+ Machine management**
**+ Performance**
**+ Diagnostics**

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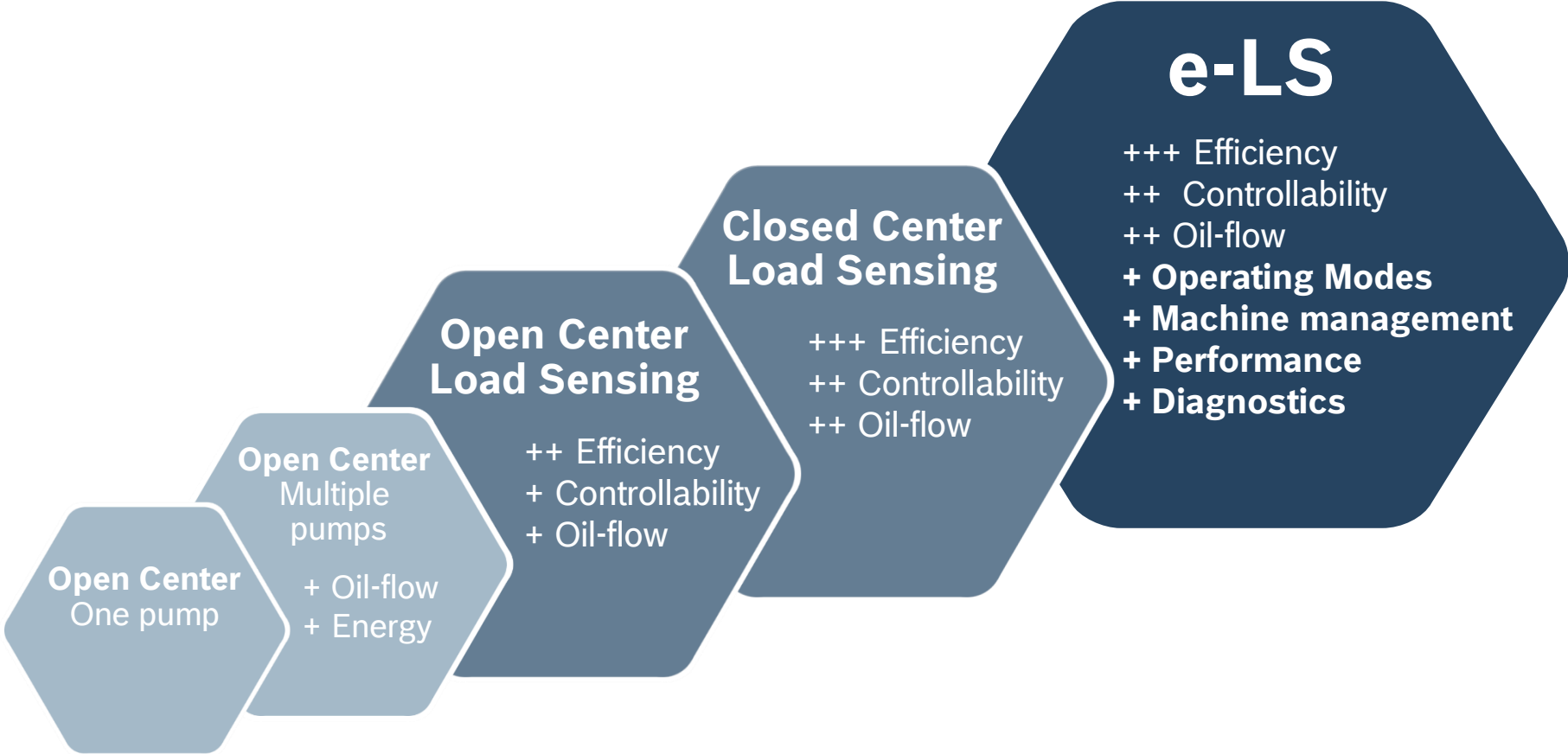
# Load Sensing Hydraulics
## Pump Pressure Settings Comparison

### Hydraulic Load Sensing (traditional)



pressure

Maximum allowable pump pressure

*Not usable*

**Fixed** *pressure cut-off*

**Limited pump pressure range**

**Fixed** *standby pressure*

*Not usable*

Minimum needed pump pressure

**time**

- No possibility to vary pump settings on demand

### Electronic Load Sensing



pressure

Maximum allowable pump pressure

**Variable** *pressure cut-off*

**Extended pump pressure range**

**Variable** *standby pressure*

Minimum needed pump pressure

**time**

+ Maximum system pressure is defined by software
+ Possibility of pressure/force limitation for single machine functions (e.g. gripper force limitation)
+ Lower standby pressure

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# Load Sensing Hydraulics
## Pump Dynamic Behavior Comparison
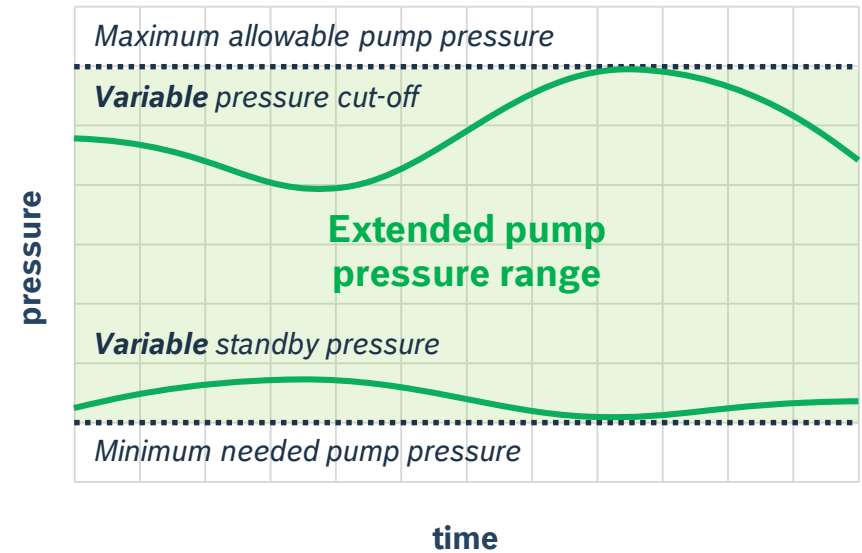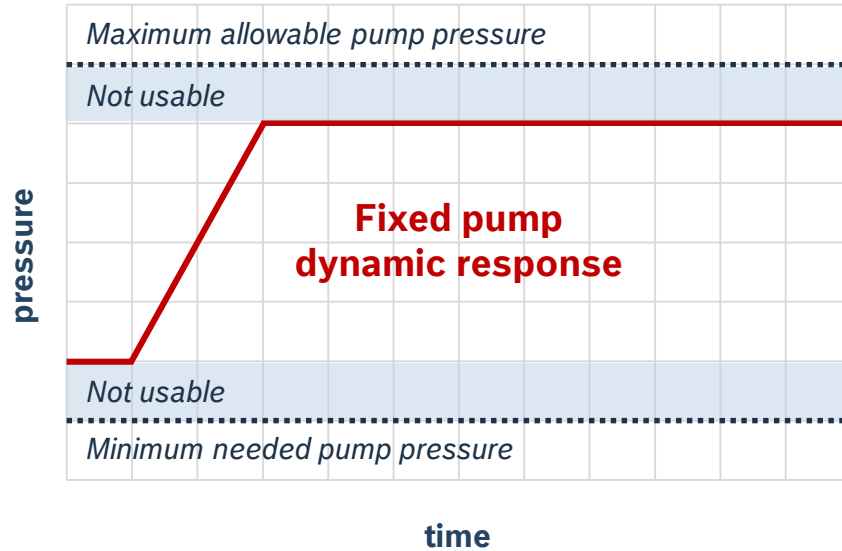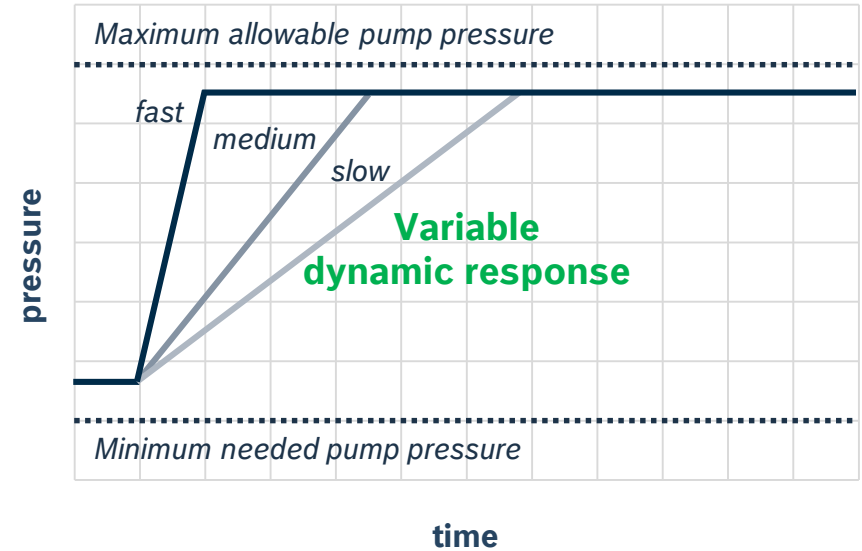
### Hydraulic Load Sensing (traditional)



- No possibility to vary pump settings on demand
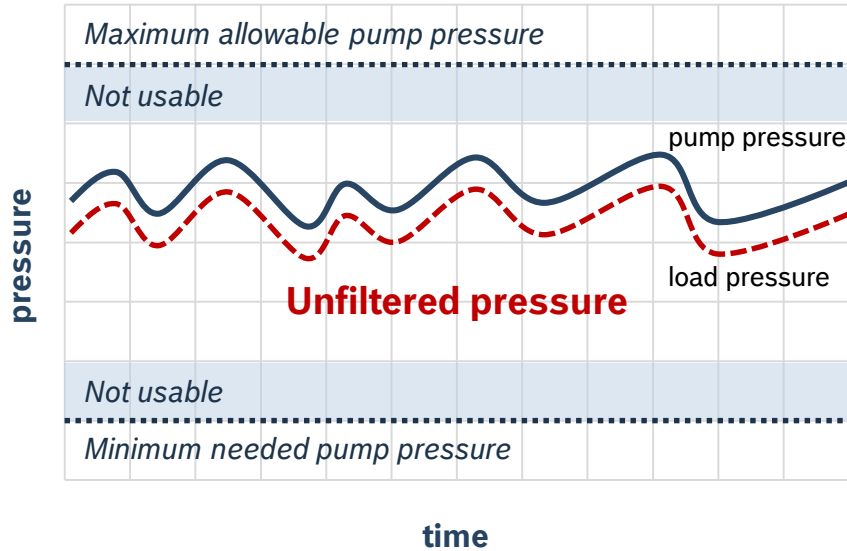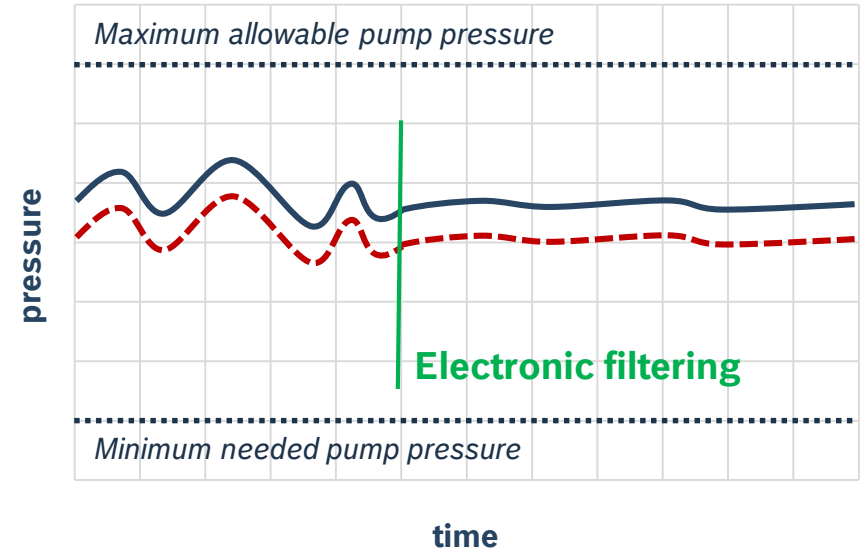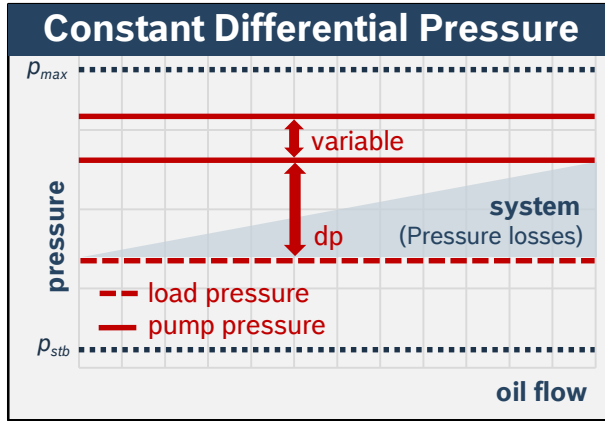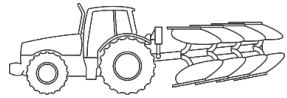
### Electronic Load Sensing



+ Avoid oscillations
+ Smooth reaction for high controllability
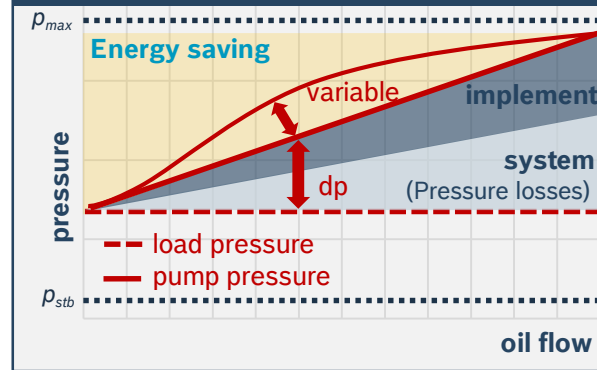+ Fast reaction for aggressive maneuvers

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# Load Sensing Hydraulics
## Pressure Behavior Comparison

**Hydraulic Load Sensing (traditional)**

*Maximum allowable pump pressure*

*Not usable*

pump pressure

load pressure

pressure

**Unfiltered pressure**

*Not usable*

*Minimum needed pump pressure*

**time**

- No possibility to vary pump settings on demand

**Electronic Load Sensing**

*Maximum allowable pump pressure*

pressure

**Electronic filtering**

*Minimum needed pump pressure*

**time**

+ Avoid oscillations
+ Smooth reaction for high controllability
+ Fast reaction for aggressive maneuvers

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# Electronic Load Sensing (eLS)
## Various Operation Modes for Different Use Cases



**Mode 1** — Constant Differential Pressure

**Mode 2** — Variable Differential Pressure

**Mode 3** — Constant Pressure Control

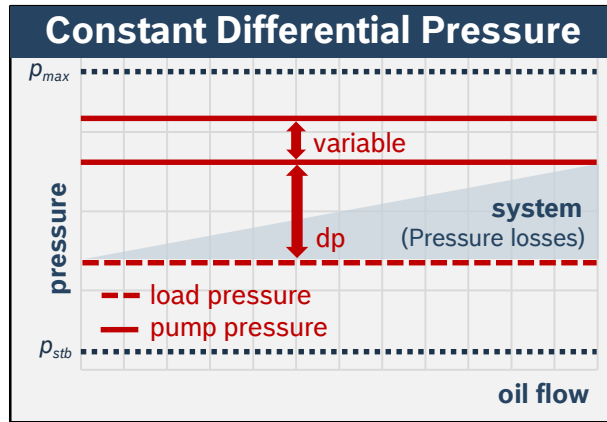**Mode 4** — Active Pressure Control

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# Electronic Load Sensing (eLS)
## Various Operation Modes for Different Use Cases

**Mode 1**

### Constant Differential Pressure

$p_{max}$

variable

dp

pressure

system (Pressure losses)

- - - load pressure
— pump pressure

$p_{stb}$

oil flow

**Mode 2**

### Variable Differential Pressure

$p_{max}$

**Energy saving**

variable    implement

dp

pressure

system (Pressure losses)

- - - load pressure
— pump pressure

$p_{stb}$

oil flow

**Mode 3**

### Constant Pressure Control

$p_{max}$

pressure

load pressure
pump pressure

$p_{stb}$

oil flow

**Mode 4**

### Active Pressure Control

$p_{max}$

pressure

e.g. ctrl sig= alpha drive pedal

pump pressure

$p_{stb}$

control signal

- **Enhanced implement performance** due to optimal compensation of pressure losses
- **Higher stability**
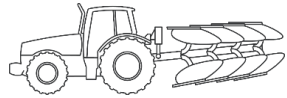- **Energy saving**

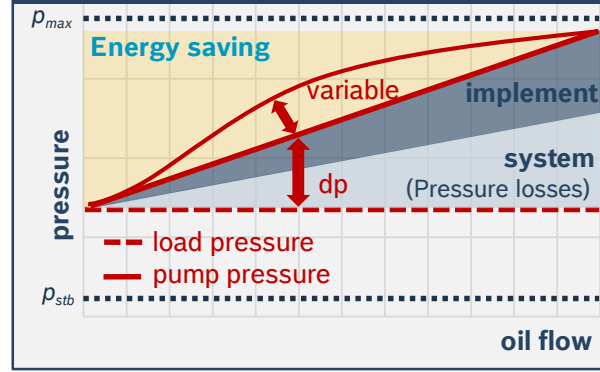**rexroth**
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# Electronic Load Sensing (eLS)
## Various Operation Modes for Different Use Cases

**Mode 1**

Constant Differential Pressure
- $p_{max}$
- variable
- pressure
- dp
- system (Pressure losses)
- load pressure
- pump pressure
- $p_{stb}$
- oil flow

**Mode 2**

Variable Differential Pressure
- $p_{max}$
- Energy saving
- Variable
- implement
- pressure
- dp
- system (Pressure losses)
- load pressure
- pump pressure
- $p_{stb}$
- oil flow

**Mode 3**

Constant Pressure Control
- $p_{max}$
- pressure
- load pressure
- pump pressure
- $p_{stb}$
- oil flow

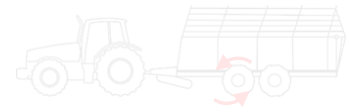**Mode 4**

Active Pressure Control

- **Fast reaction and increased stability** for certain implements
- **Working point optimization** with adjustable constant pressure for secondary controlled implements
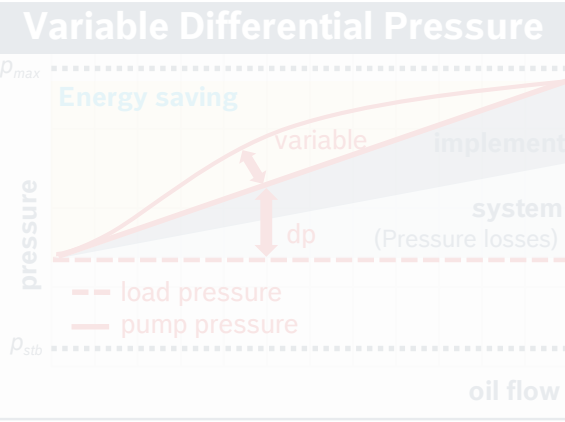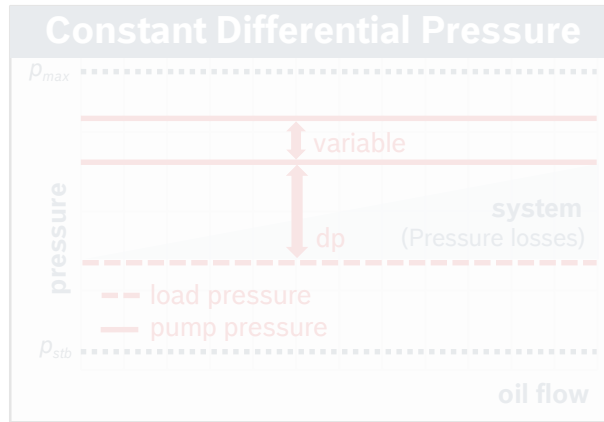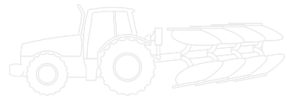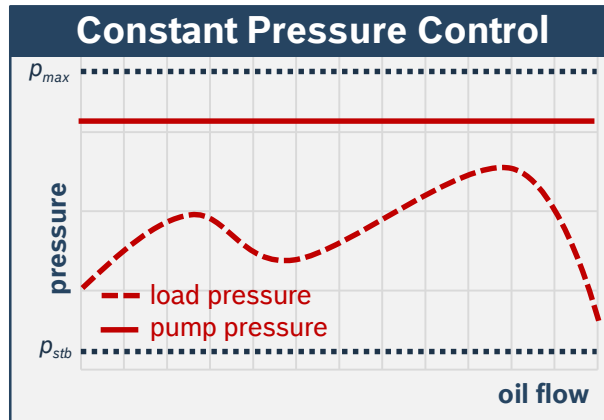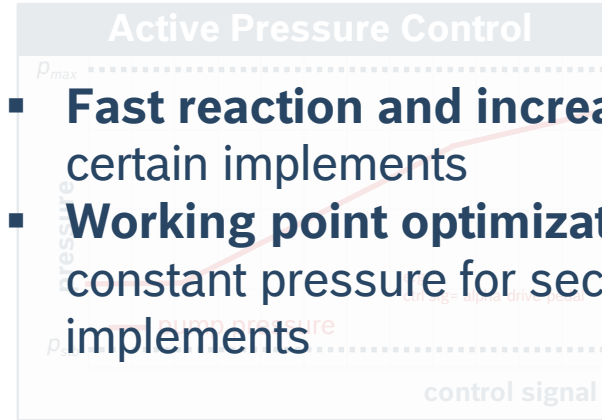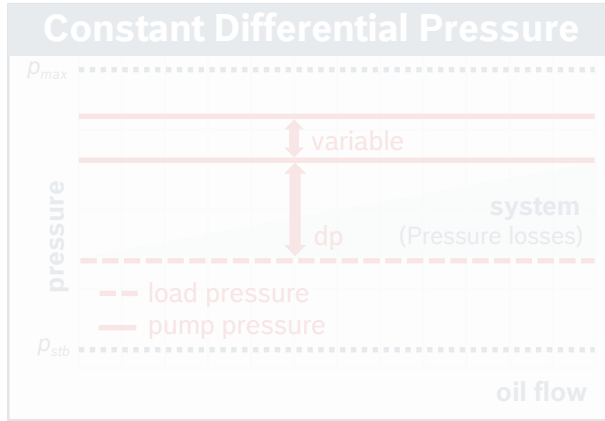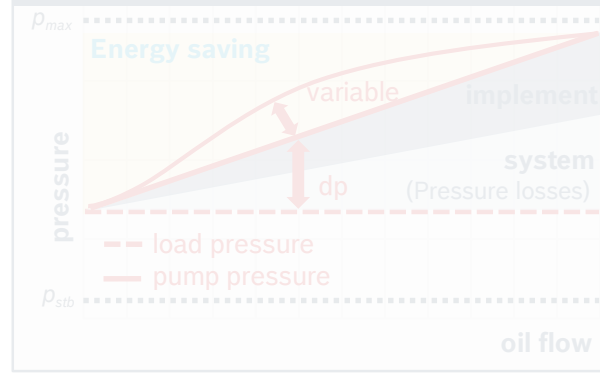
control signal

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# Electronic Load Sensing (eLS)
## Various Operation Modes for Different Use Cases

**Mode 1**

**Constant Differential Pressure**

$p_{max}$

variable

pressure

dp

system
(Pressure losses)

--- load pressure
— pump pressure

$p_{stb}$

oil flow

**Mode 2**

**Variable Differential Pressure**

$p_{max}$

Energy saving

Variable

implement

pressure

dp

system
(Pressure losses)

--- load pressure
— pump pressure

$p_{stb}$

oil flow

**Mode 3**

**Constant Pressure Control**

$p_{max}$
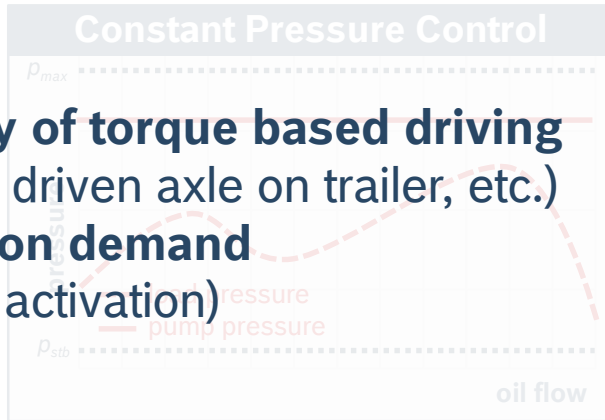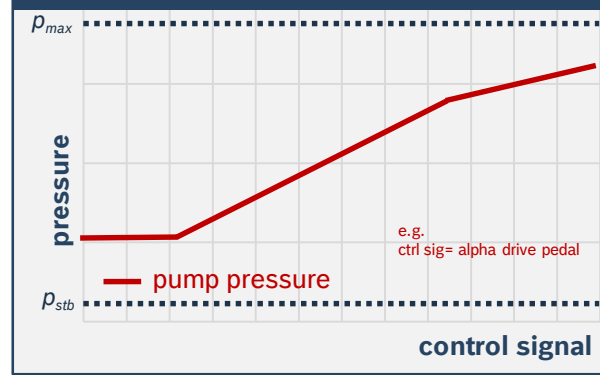
■ **Possibility of torque based driving**
(additional driven axle on trailer, etc.)

■ **Pressure on demand**
(front axle activation)

pressure

— pump pressure

$p_{stb}$

oil flow

**Active Pressure Control**

$p_{max}$

pressure

e.g.
ctrl sig= alpha drive pedal

— pump pressure

$p_{stb}$

control signal

**Mode 4**

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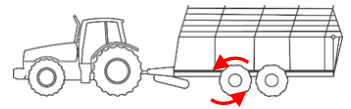
# Load Sensing Hydraulics
## Selecting the Optimized Settings for Each Individual Implement

**Automatic**

**Remote**

**Manual**

eLS

**Electronic Load Sensing**

LS valve stack

psys

consumer 1

pLS

consumer 2

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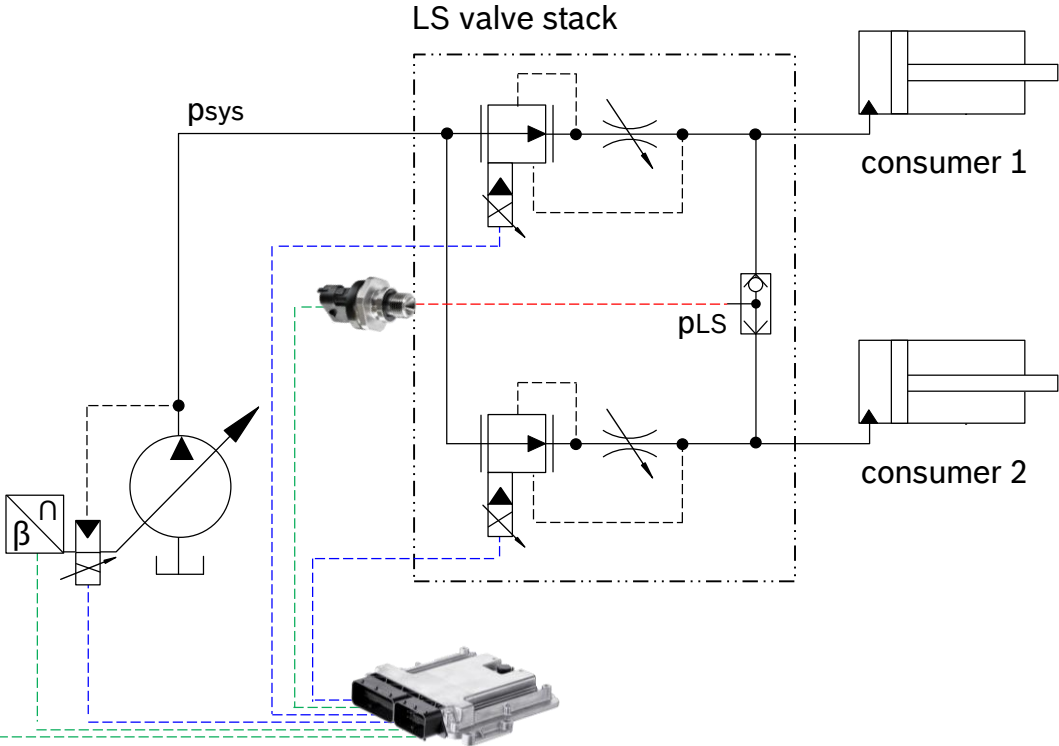
# Load Sensing Hydraulics
## eLS with Steering
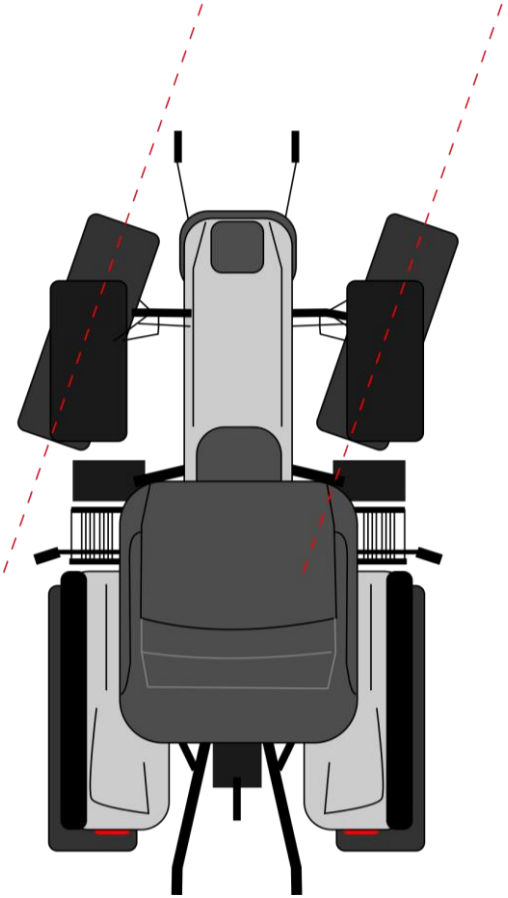


**Electronic Load Sensing**

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# *Practical Examples*

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# Electronic Load Sensing (eLS) Hydraulics

**Active Pressure Control**

$p_{max}$

pressure

e.g.
ctrl sig= alpha drive pedal

— pump pressure

$p_{stb}$

control signal
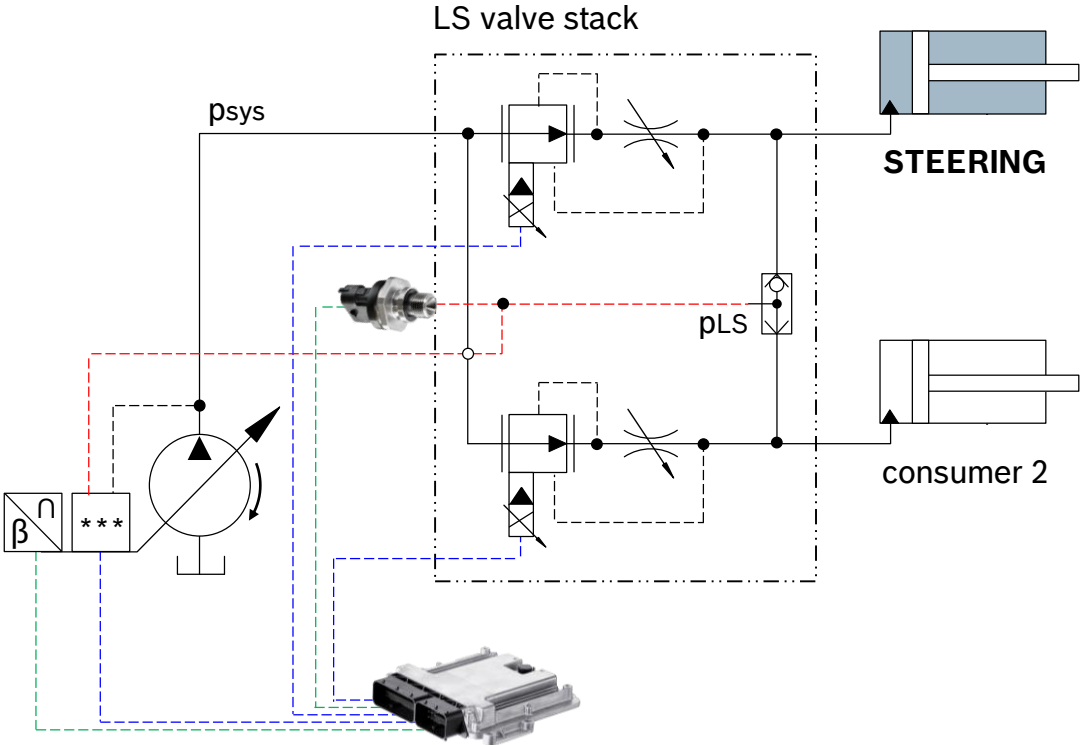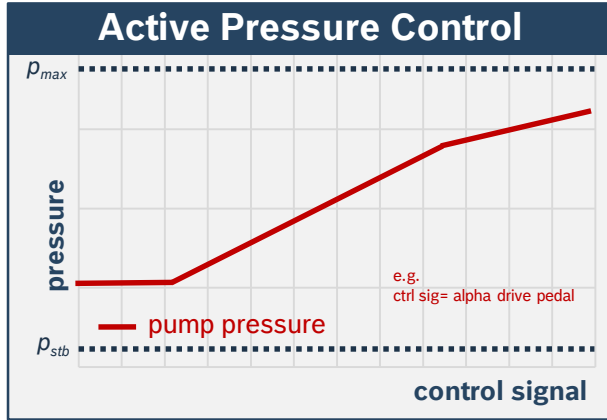
Griper Control

| Hydraulic Load Sensing (LS) | | Electronic Load Sensing (eLS) |
|---|---|---|
| Pressure Too Low | Pressure Too High | Optimal and repeatable pressure setting |

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# Electronic Load Sensing (eLS) Hydraulics

## Variable Differential Pressure

Energy saving

Variable

implement

$p_{max}$

pressure

dp

system (Pressure losses)

— — load pressure

—— pump pressure

$p_{stb}$

oil flow

Hydraulic Load Sensing (LS)

Electronic Load Sensing (eLS)

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# Electronic Load Sensing (eLS) Hydraulics



Maximum allowable pump pressure
fast
medium
slow
**Variable dynamic response**
pressure
Minimum needed pump pressure
**time**
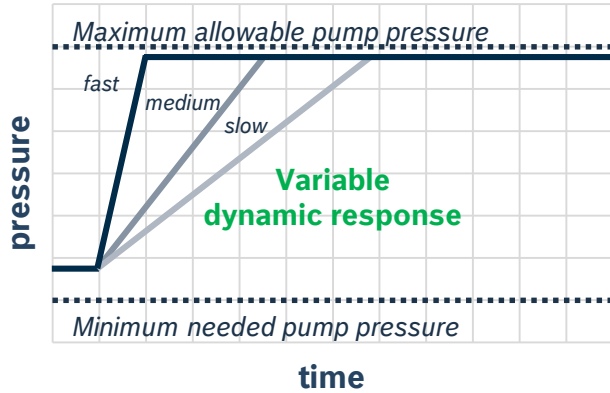


Front-loader Lifting Control
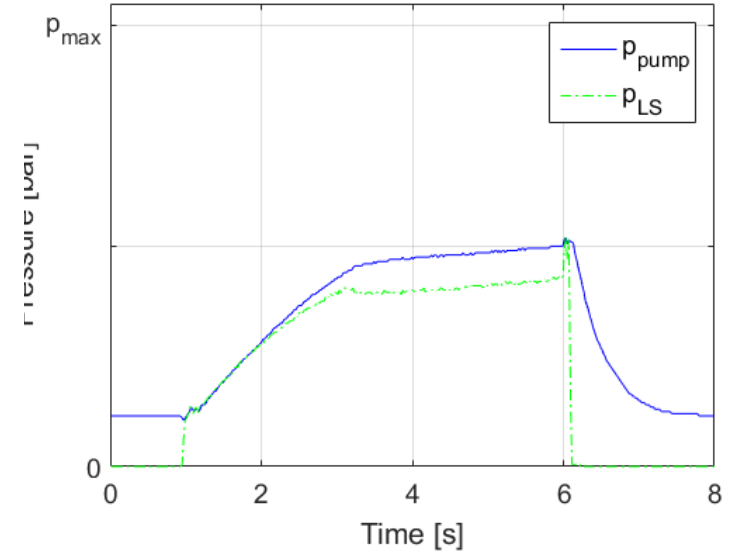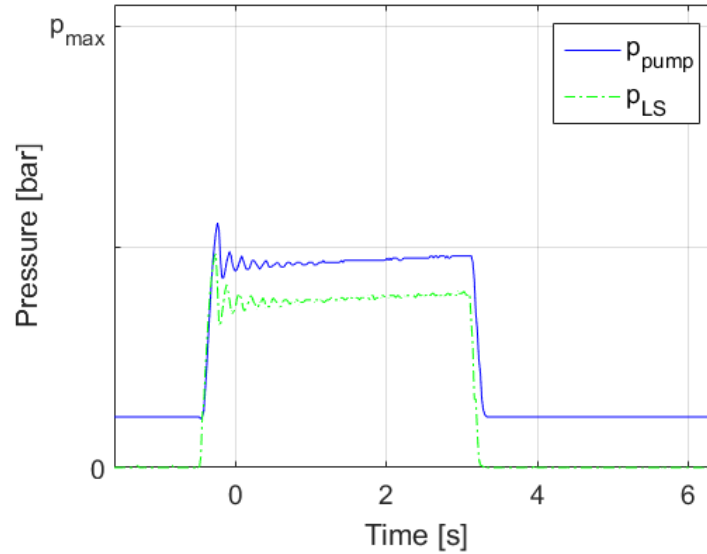
## Electronic Load Sensing (eLS)



$p_{max}$

$p_{pump}$
$p_{LS}$

Pressure [bar]

Time [s]



$p_{max}$

$p_{pump}$
$p_{LS}$

Pressure [bar]

Time [s]

20

DC-MH/ENG5-NA | 29/05/2019

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# Electronic Load Sensing (eLS) Hydraulics



Maximum allowable pump pressure

pressure

**Electronic filtering**

Minimum needed pump pressure

**time**



Fan Control



## Hydraulic Load Sensing (LS)

Pressure [bar] — $p_{max}$ ... 0

$p_{pump}$
$p_{LS\ PB}$

Time [s]: 0 2 4 6 8 10 12 14

Speed [rpm] — $n_{max}$ ... 0

$n_{fandrive}$

Time [s]: 0 2 4 6 8 10 12 14

## Electronic Load Sensing (eLS)

Pressure [bar] — $p_{max}$ ... 0

$p_{pump}$
$p_{LS\ PB}$

Time [s]: 0 2 4 6 8 10 12 14

Speed [rpm] — $n_{max}$ ... 0

$n_{fandrive}$

Time [s]: 0 2 4 6 8 10 12 14

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# Electronic Load Sensing (eLS)
## Enhanced Benefits for Most Efficient Working Results

- **Improved Efficiency** due to optimized differential pressure
- **Increased power and improved response** of the implement, due to variable pressure limits
- **Individual system adaption**
- **Easy to use** with predefined modes
- **High flexibility**, software-based variant handling
- **Less installation space**
- **Connectivity option** for system monitoring

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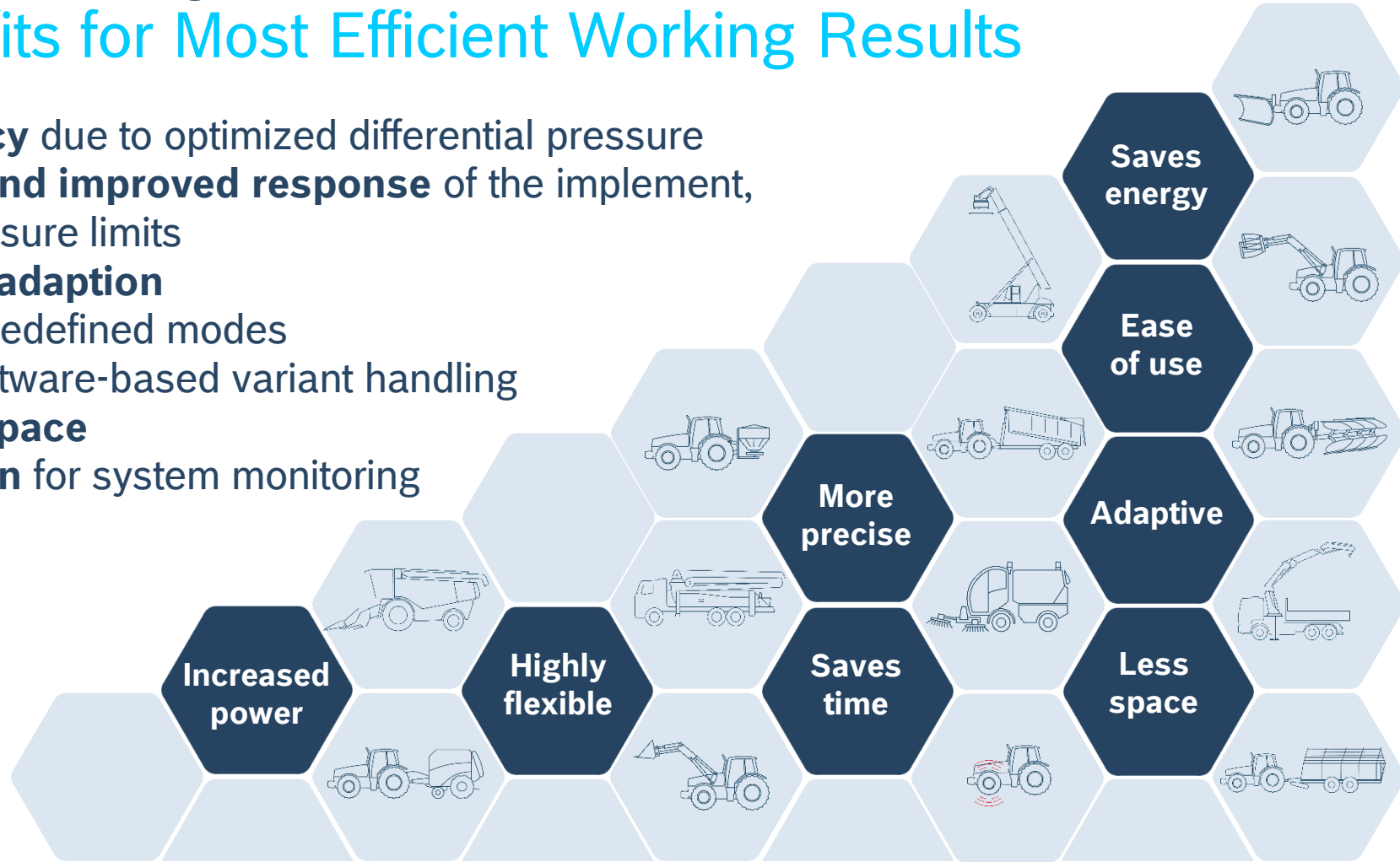
# Thank You!

Enrique Busquets
Enrique.Busquets@bosch.com